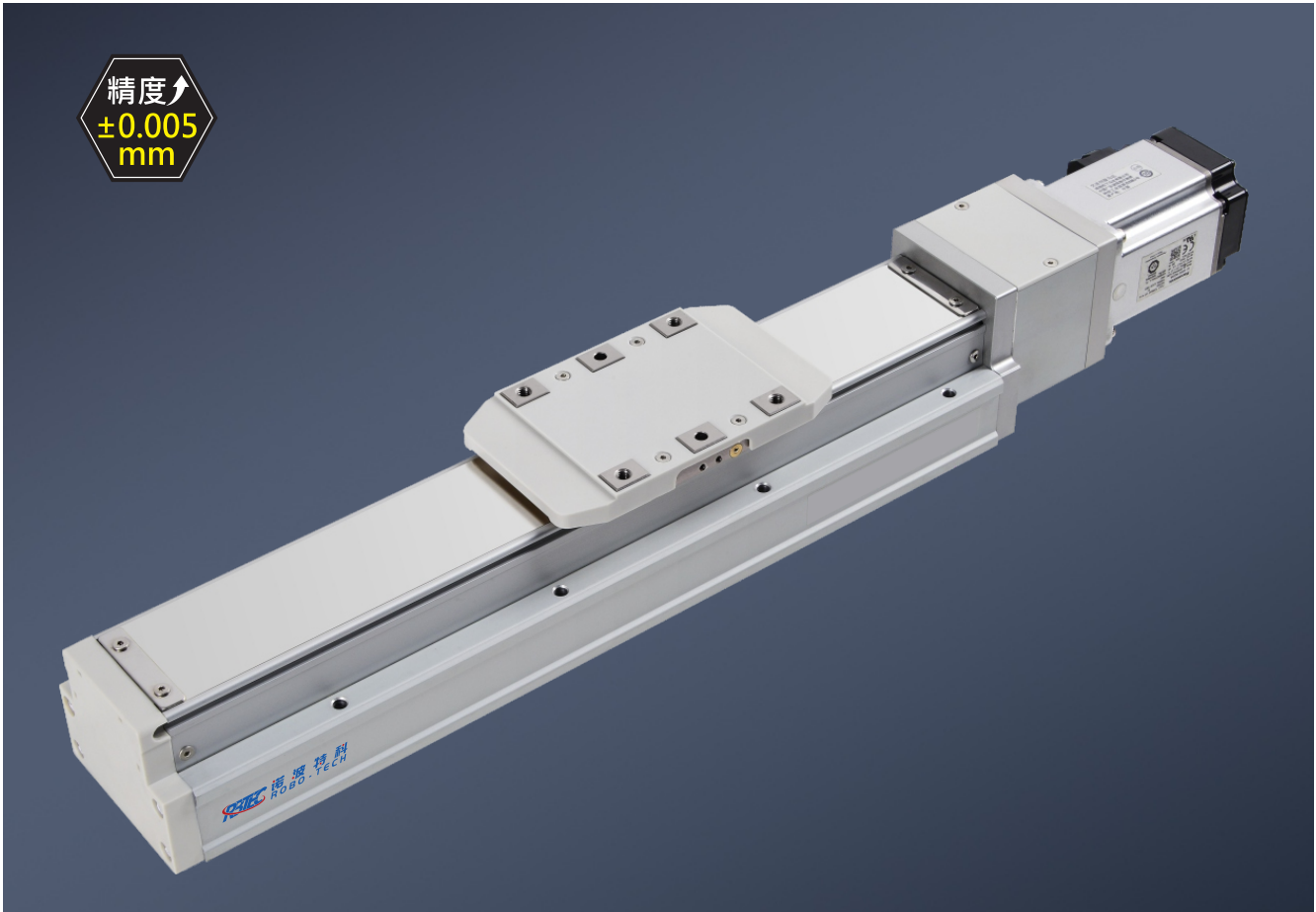
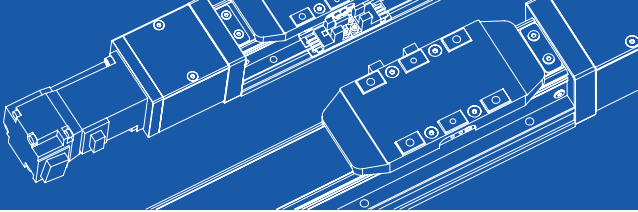




精度 ±0.005 mm

最大行程 1250mm

最高速度 1200mm/s

电机容量 200W

最大可搬重量 50kg

滚珠丝杆 ø16mm

型号表示方式 Ordering Method

RGH8 - 05 - 100 - E - M20B\* - C 4 - 01

本体型号 Model

行程 Stroke

转造级 Rolled Ballscrews 50-1250 mm 研磨级 Grind Ballscrews 50-700mm \*间隔50 Interval 50 mm

电机位置 Motor Position

E 电机外露 Motor Exposed L 电机左折 Motor Left Side R 电机右折 Motor Right Side M 电机下折 Motor Bottom Side

电机厂牌、功率 Motor Brand · Power Output

M 三菱 Mitsubishi P 松下 Panasonic Y 安川 Yaskawa 20 200W B T 台达 Delta

原点感应器 Origin Sensor

外挂型 Outside C 电机侧 Motor Side D 反电机侧 Opposite Motor Side 无 SENSOR No Sensor E 无 SENSOR No Sensor

限位传感器 Limit Sensor

外挂型 Outside 3 1只 1 Pc 4 2只 2 Pc 无 SENSOR No Sensor 5 无 SENSOR No Sensor

\*选用G研磨级螺杆，有行程限制，详见基本式样 G precision-level grind ball screws are not available in all stroke lengths, please consult the model datasheet.

\*若无刹车则B不表示。 If There is No Brake, B Does Not Indicate.

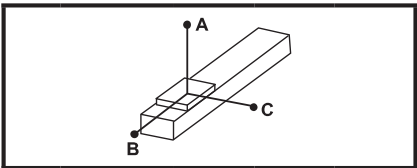
\*选择行程50时，有以下限制： When the stroke is 50mm, the sensor installation has the following restrictions. 1.原点与极限需放置与不同侧。 Home sensor and limit sensor has to be installed on the different side of body. 2.滑座左右两侧均需安装感应片。 Both sides of slider need to install the sensor trigger device

基本式样 Specification

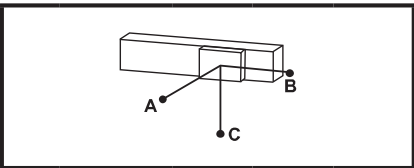
| 性能<br>Performance          | 滚珠丝杆 等级代号 Ballscrew Accuracy Grade Code |                 |      | —                            | G                            |
|----------------------------|-----------------------------------------|-----------------|------|------------------------------|------------------------------|
|                            | 滚珠丝杆 等级 Ballscrew Accuracy Grade        |                 |      | C7 转造 C7 Rolled Ballscrew    | C5 研磨 C5 Grind Ballscrew     |
|                            | 位置重复精度 Repeatability                    |                 | mm   | ±0.005                       |                              |
|                            | 标准行程 Stroke Pitch                       |                 | mm   | 50-1250mm / 50间隔<br>Interval | 50-700mm / 50 间隔<br>Interval |
|                            | 滚珠丝杆 导程 Ball Screw Lead                 |                 | mm   | 5                            | 1020                         |
|                            | 最高转速 Maximum Rotating Speed             |                 | rpm  | 3600                         | 36003600                     |
|                            | 最高速度 Maximum Linear Speed※1※2           |                 | mm/s | 300                          | 6001200                      |
|                            | 最大可搬重量<br>Maximum Payload               | 水平使用 Horizontal | kg   | 50                           | 3018                         |
|                            |                                         | 垂直使用 Vertical   | kg   | 15                           | 83                           |
|                            | 定格推力 Rated Thrust                       |                 | N    | 683                          | 341174                       |
| 最大加速度 Maximum Acceleration |                                         | G               | 0.3  | 0.30.6                       |                              |
| 部品<br>Parts                | AC伺服电机 容量 AC Servo Motor Output         |                 | W    | 200                          |                              |
|                            | 滚珠丝杆外径 Ball Screw Ø                     |                 | mm   | Ø16                          |                              |
|                            | 联轴器 Coupling                            |                 | mm   | Ø10-Ø11/14                   |                              |
|                            | 原点及限位感应器<br>Origin & Limit Sensor※      | 外挂 Outside      |      | EE-SX674(NPN)                |                              |

※1 电机加减速设定0.2秒。 Acceleration and deacceleration value is set 0.2 second. ※2 长行程时，会产生滚珠丝杆偏摆，需将速调降（线速度请参阅尺寸图下文方表格） During in a long stroke, it causes ballscrew deflection, the speed must reduce. (Please refer to the linear velocity from the data sheet below the dimension graph.) ※3 有关传感器另外的选型，如有需求请咨询我司业务。 For additional selection of sensors, please contact our business it you have any requirements.

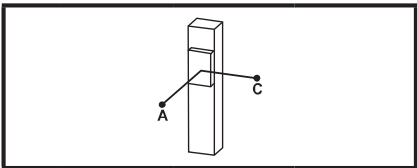
容许负载悬矩表 Allowable Overhang



(单位 Unit : mm)



(单位 Unit : mm)



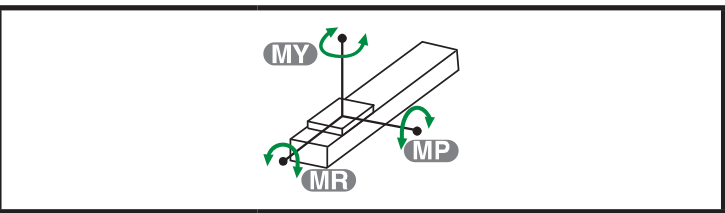
(单位 Unit : mm)

| 水平安装 Horizontal Installation |      | A    | B   | C   |
|------------------------------|------|------|-----|-----|
| 导程 5 Lead                    | 20kg | 1275 | 127 | 197 |
|                              | 30kg | 725  | 72  | 112 |
|                              | 50kg | 380  | 38  | 58  |
| 导程 10 Lead                   | 10kg | 1269 | 246 | 345 |
|                              | 20kg | 588  | 104 | 148 |
|                              | 30kg | 352  | 58  | 82  |
| 导程 20 Lead                   | 5kg  | 988  | 380 | 440 |
|                              | 10kg | 471  | 174 | 204 |
|                              | 18kg | 248  | 88  | 104 |

| 壁挂安装 Wall Installation |      | A   | B   | C    |
|------------------------|------|-----|-----|------|
| 导程 5 Lead              | 20kg | 197 | 127 | 1275 |
|                        | 30kg | 112 | 72  | 725  |
|                        | 50kg | 58  | 38  | 380  |
| 导程 10 Lead             | 10kg | 345 | 246 | 1269 |
|                        | 20kg | 148 | 104 | 588  |
|                        | 30kg | 82  | 58  | 352  |
| 导程 20 Lead             | 5kg  | 440 | 380 | 988  |
|                        | 10kg | 204 | 174 | 471  |
|                        | 18kg | 104 | 88  | 248  |

| 垂直安装 Vertical Installation |       | A   | C   |
|----------------------------|-------|-----|-----|
| 导程 5 Lead                  | 5kg   | 647 | 647 |
|                            | 10kg  | 323 | 323 |
|                            | 15kg  | 215 | 215 |
| 导程 10 Lead                 | 3kg   | 937 | 937 |
|                            | 5kg   | 561 | 561 |
|                            | 8kg   | 351 | 351 |
| 导程 20 Lead                 | 2kg   | 990 | 990 |
|                            | 2.5kg | 792 | 792 |
|                            | 3kg   | 660 | 660 |

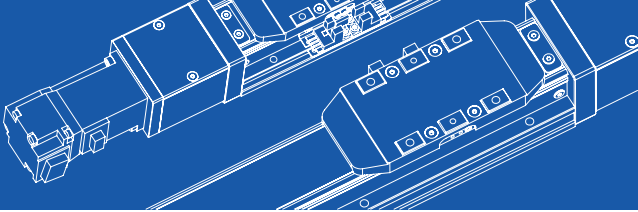
静态容许负载惯量 Static Allowable Load Inertia



(单位 Unit : N.m)

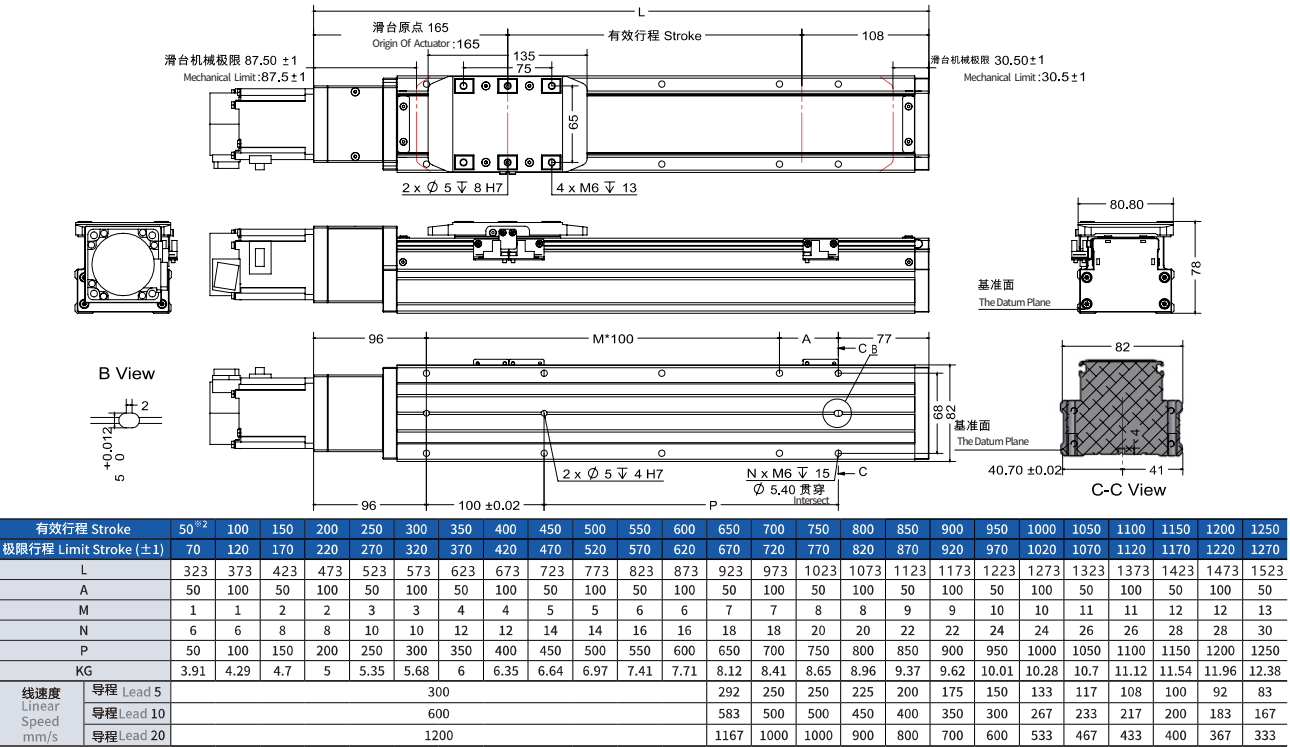
|    |     |
|----|-----|
| MY | 318 |
| MP | 318 |
| MR | 626 |

\*力矩表所表示的数据，代表荷重的重心位置单一方向容许悬出的长度。 The data represented by the moment table is the center of gravity of the load.The length of the overhang is allowed in a single direction. \*符合型录规范的正常使用下，保证寿命为10000公里。 Operation life is 10,000km when the product is using under the specified conditions. \*倒吊使用无法套用标准规范，如有需求请咨询我司业务。 Data information is not for ceiling-mount inverse use. Contact us for the details if you want to apply ceiling-mount inverse usage.



E 电机外露 Motor Exposed

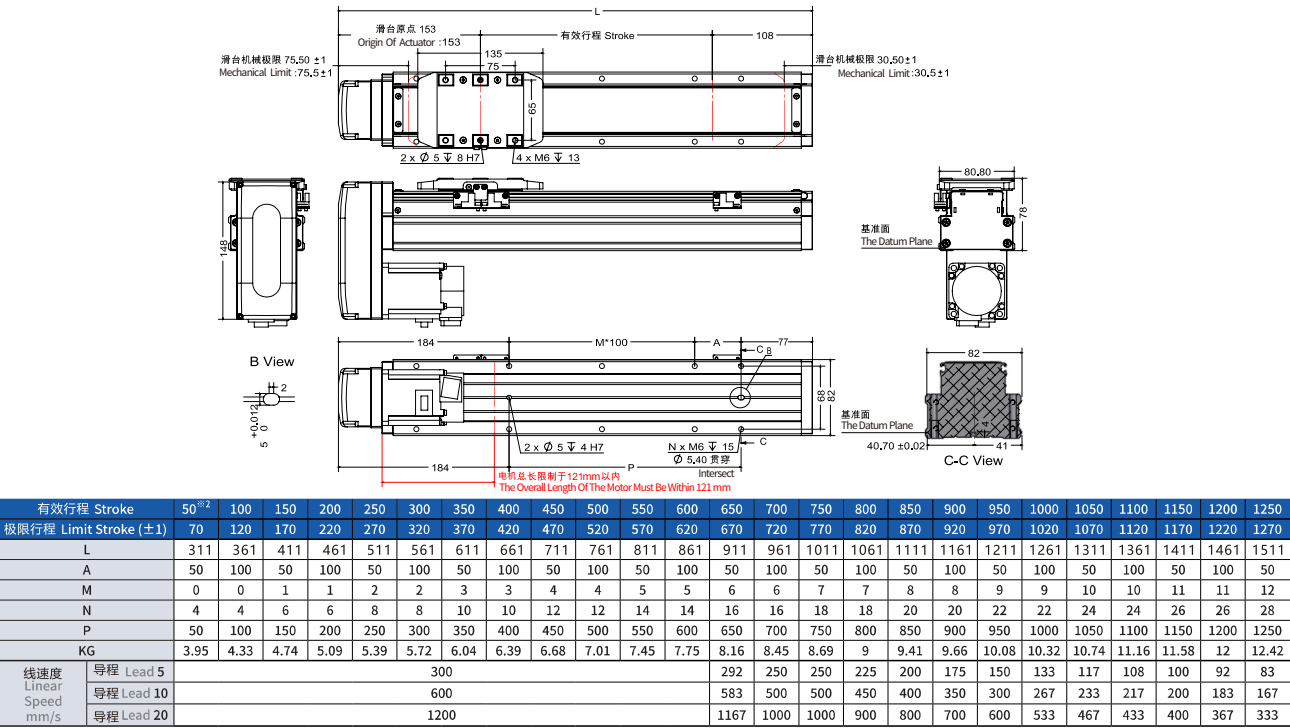
单位 Unit: mm



※2行程50时，因本体上锁式固定孔会被滑座遮住，仅能使用4支螺丝固定，建议客户本体下锁式固定孔锁附。When the stroke is 50mm, if fixing the body from the top to the bottom, the fixing hole will be blocked by slider and only can be uses 4 screws to fix,as a result, suggest that fixing actuator body from the bottom to the top.

M 电机下折 Motor Bottom Side

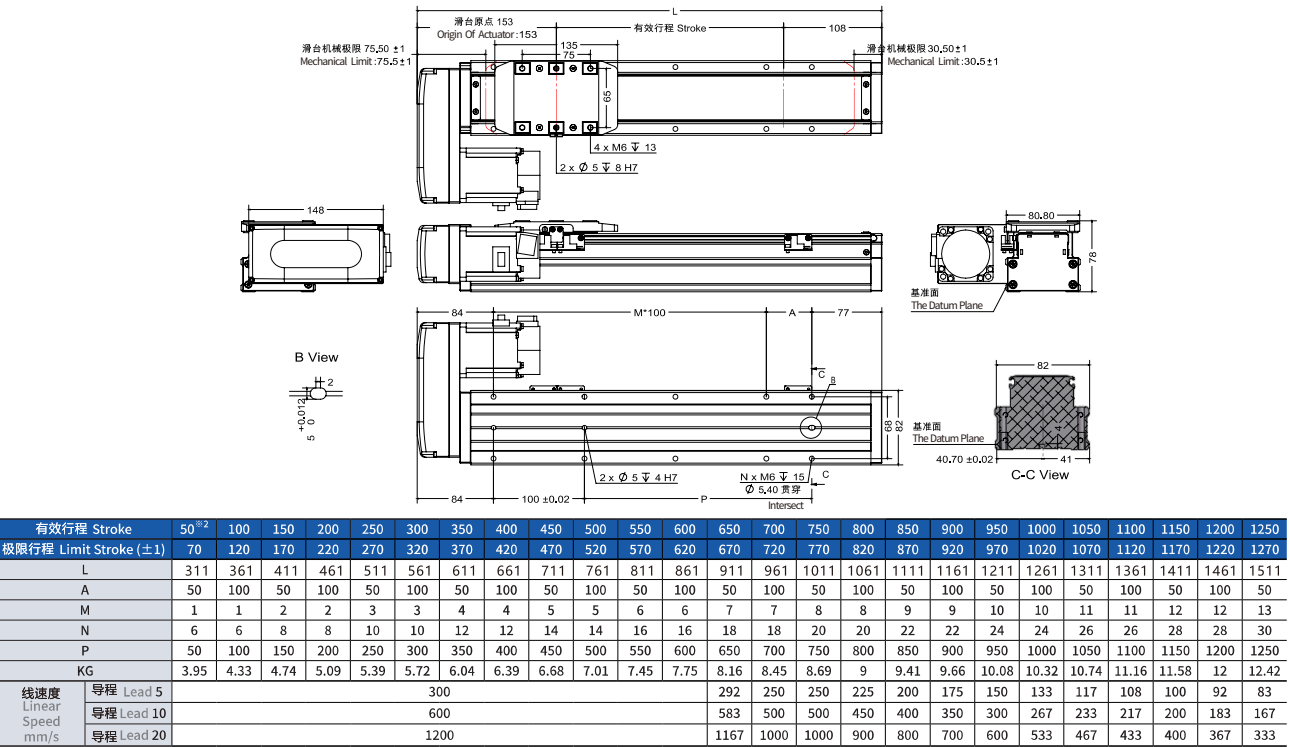
单位 Unit: mm



※1 电机下折时，若选用刹车电机，或是超出电机总长度限制时，无法套用标准PIN孔，如有需求，请联系我司业务。When motor with brake assembled on lower side, or the total length over than spec limit, it may not use standard pinhole. Please contact our sales department if you need more information & requirement.  
※2 行程50时，因本体上锁式固定孔会被滑座遮住，仅能使用4支螺丝固定，建议客户本体下锁式固定孔锁附。When the stroke is 50mm, if fixing the body from the top to the bottom, the fixing hole will be blocked by slider and only can be uses 4 screws to fix,as a result, suggest that fixing actuator body from the bottom to the top.

L 电机左折 Motor Left Side

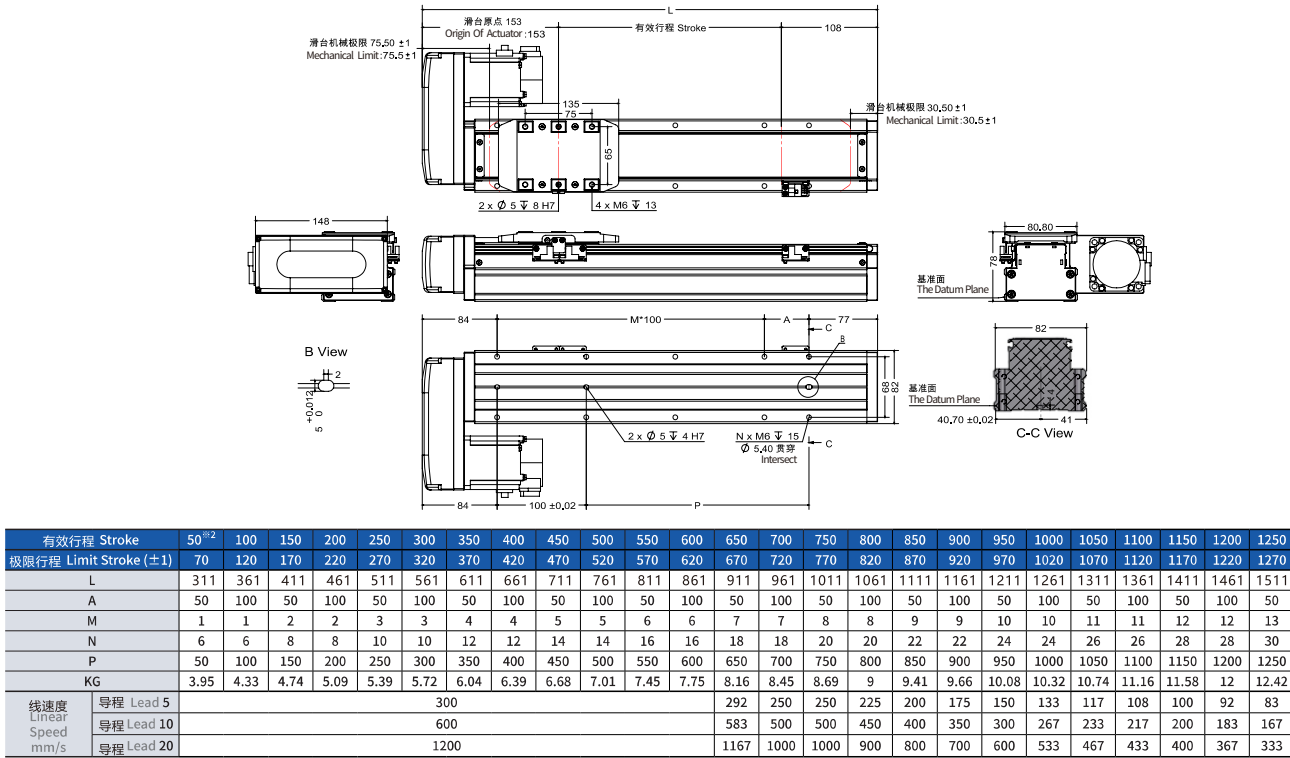
单位 Unit: mm



※2行程50时，因本体上锁式固定孔会被滑座遮住，仅能使用4支螺丝固定，建议客户本体下锁式固定孔锁附。When the stroke is 50mm, if fixing the body from the top to the bottom, the fixing hole will be blocked by slider and only can be uses 4 screws to fix,as a result, suggest that fixing actuator body from the bottom to the top.

R 电机右折 Motor Right Side

单位 Unit: mm



※2行程50时，因本体上锁式固定孔会被滑座遮住，仅能使用4支螺丝固定，建议客户本体下锁式固定孔锁附。When the stroke is 50mm, if fixing the body from the top to the bottom, the fixing hole will be blocked by slider and only can be uses 4 screws to fix,as a result, suggest that fixing actuator body from the bottom to the top.